

# **Isolated Non-Equilibrium Systems in Contact**

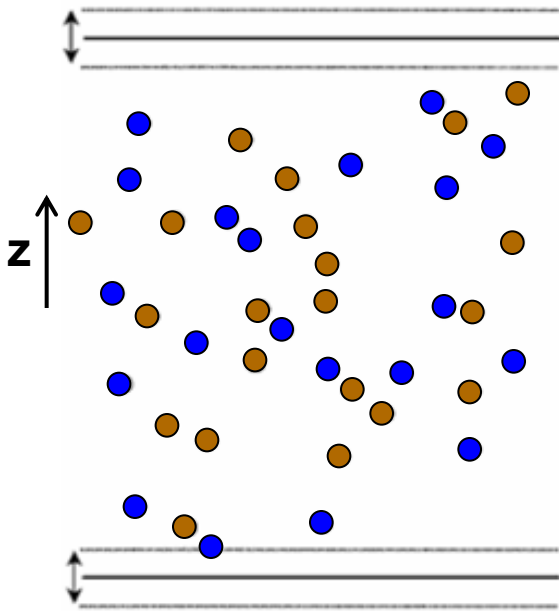
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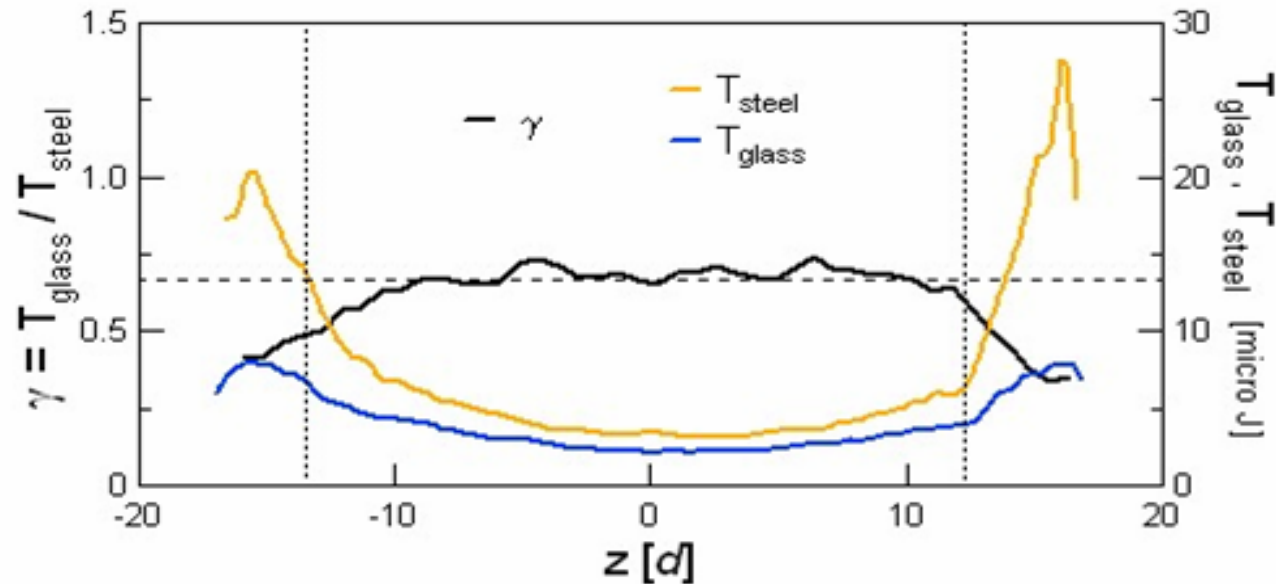
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# Isolated Non-Equilibrium Systems in Contact



- Shake a box with 2 types of grains
- Measure:  $T_G =$  average energy per particle
- Energy not equipartitioned



# Isolated **Non-Equilibrium** Systems in Contact

- Shake a box with 2 types of grains
- Measure:  $T_G$  = average energy per particle
- Energy not equipartitioned
- Not that surprising:
  - restitution coefficient
  - energy dissipation rate
  - steady-state energy
- Maybe fluctuation-dissipation relations encode deeper meaning of temperature ?

# Isolated **Non-Equilibrium** Systems in Contact

- Shake a box with 2 types of grains
- Measure:
  - Fluctuation (diffusion)
  - Response (mobility)
- Define:  $T_{FD} = \frac{\text{Fluctuation}}{\text{Response}}$
- Simulations:  $T_{FD}(A) \approx T_G(A) \neq T_{FD}(B) \approx T_G(B)$
- Maybe fluctuation-dissipation relations encode deeper meaning of temperature ?

???

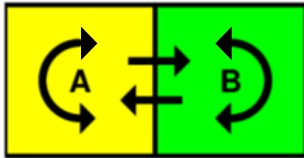
# Isolated Non-Equilibrium Systems in Contact

- Entropy,  $S$ , maximized
- Energy,  $E$ , conserved



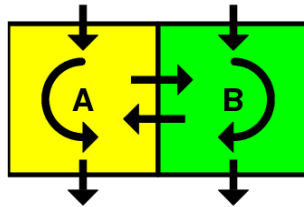
- Temperature,  $T = \left( \frac{\partial S}{\partial E} \right)^{-1}$  equalizes

# Isolated Non-Equilibrium Systems in Contact



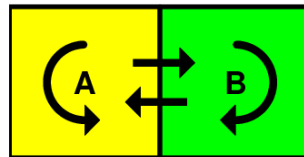
**Equilibrium (isolated & detailed balance)**

$$E = \text{const.}, \max(S) \Rightarrow T(A) = T(B)$$



**Driven Dissipative (open & no detailed balance)**

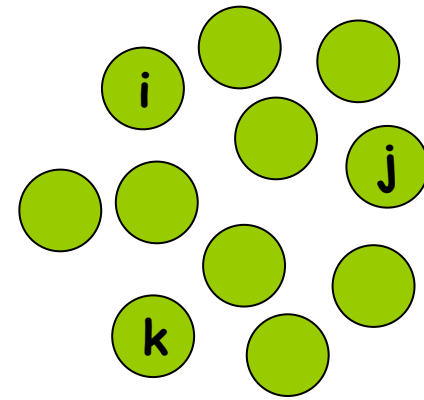
$$E \neq \text{const.}, S?, T_{\text{eff}}(A) \stackrel{?}{=} T_{\text{eff}}(B)$$



**Isolated & no detailed balance**

**Non-equilibrium, Simpler**

# Minimal Modeling



- Particles  $1 \leq i \leq N$  have energies  $\{e_i > 0\}$
- Mean-field interactions (randomly chose  $i, j, k$ )
- Energy



$$e_i \longrightarrow z\alpha(e_i + e_j)$$

$$e_j \longrightarrow (1-z)\alpha(e_i + e_j)$$

$$~~(1-\alpha)(e_i + e_j)~~$$

$0 \leq z \leq 1$  random (uniform dist.)  
 $0 \leq \alpha \leq 1$  restitution coefficient

- $\alpha = 1$  (Ulam 1980)  $\rightarrow$  system equilibrates (H-theorem)
- Dissipation ( $\alpha < 1$ )  $\rightarrow$  system cools to  $e_i = 0$
- Connect to thermostat  $\rightarrow$  (open) non-equilibrium steady state

Srebro & Levine 2004

## Isolated non-equilibrium model:

- Give dissipated energy to 3<sup>rd</sup> particle

$$e_k \longrightarrow e_k + (1-\alpha)(e_i + e_j)$$

# Isolated System is Far from Equilibrium

- Consider subsystem of 1 particle in large isolated system
- Measure rates of transitions between its states

$$R(e \rightarrow e') = W(e \rightarrow e' | e) P(e)$$

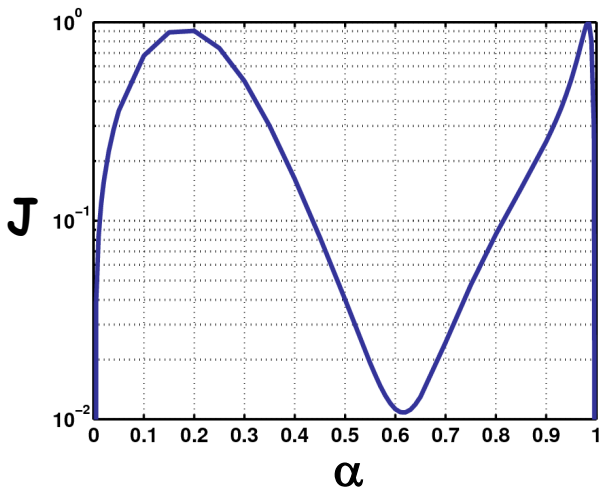
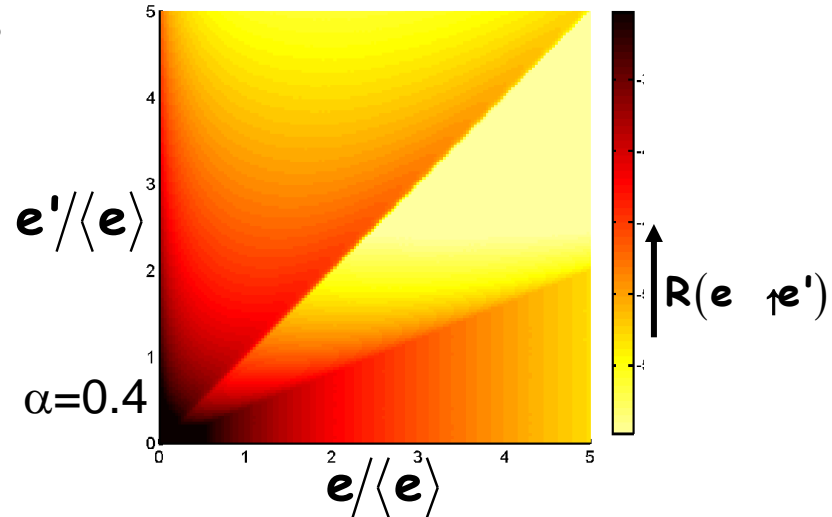
Rate at which transition occur

Probability for transition, given  $e$

- Microscopic irreversibility

→ **Detailed-balance violation:**

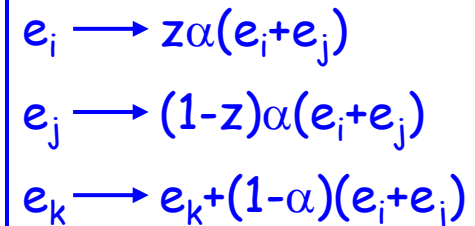
$$R(e \rightarrow e') \neq R(e' \rightarrow e)$$



**Quantify distance from equilibrium with net probability current:**

Zia & Schmittmann 2006

$$J \equiv \int [R(e \rightarrow e') - R(e' \rightarrow e)]^2 d e d e'$$

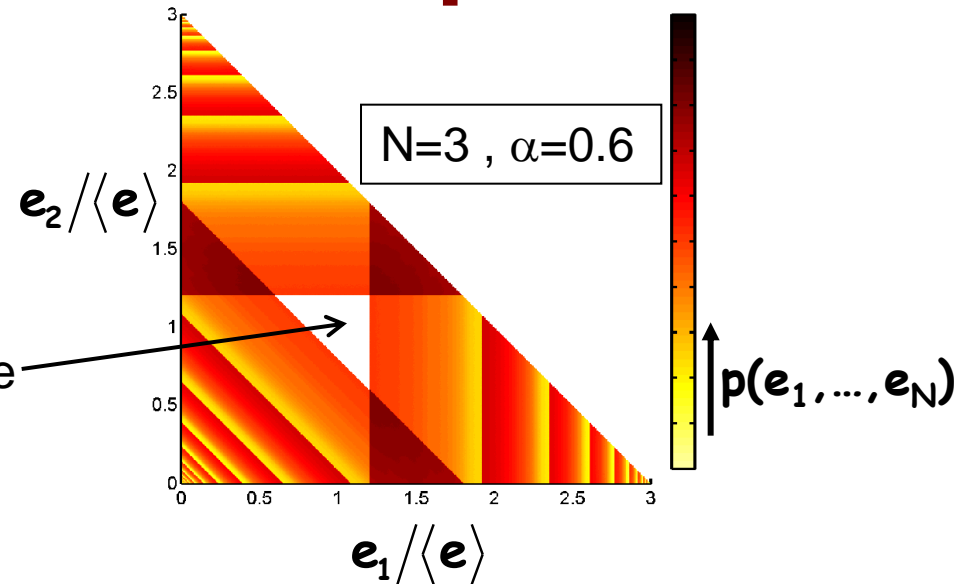


# Isolated System is Far from Equilibrium

- Microscopic irreversibility  
→ **Ergodicity breaking**

inaccessible region in configuration space

- Microscopic irreversibility  
→ **Detailed-balance violation**



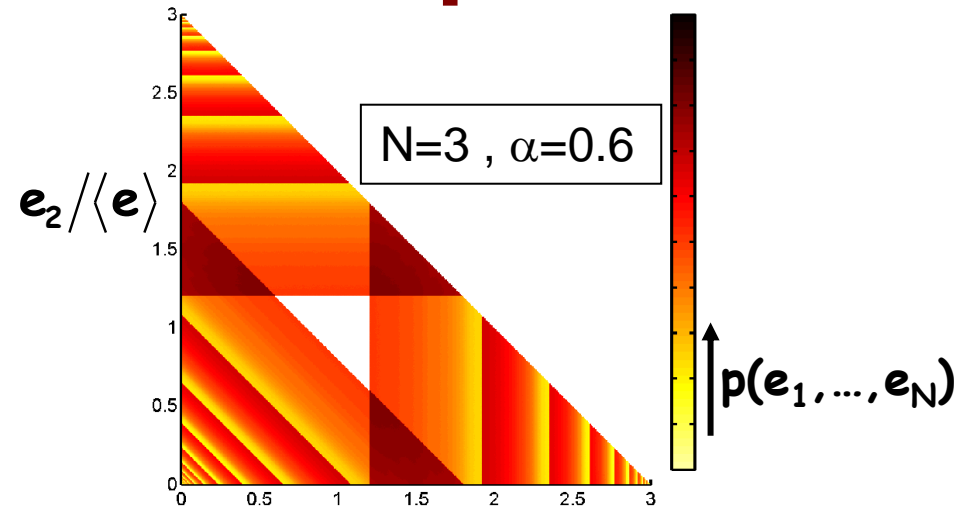
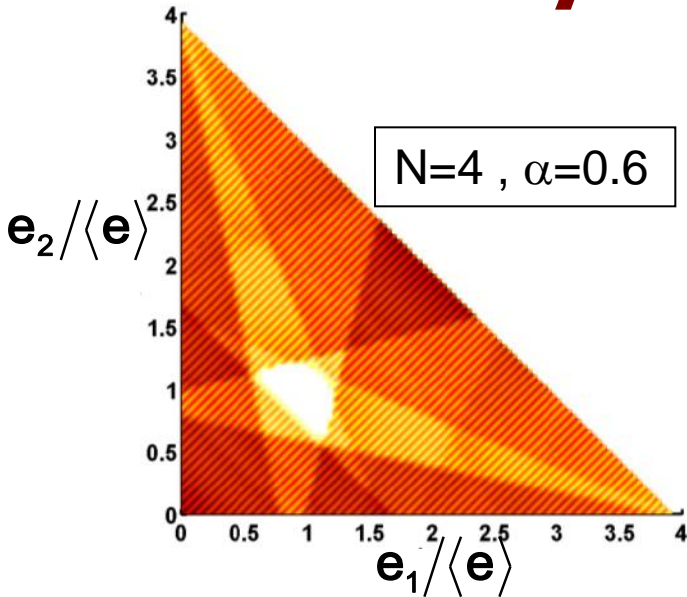
Ask what transition brings the system to  $\mathbf{e}_1 = \mathbf{e}_2 = \dots = \mathbf{e}_N = E/N$

$$\left. \begin{aligned}
 e_i &\rightarrow z\alpha(e_i + e_j) = E/N \\
 e_j &\rightarrow (1-z)\alpha(e_i + e_j) = E/N \\
 e_k &\rightarrow e_k + (1-\alpha)(e_i + e_j) = E/N
 \end{aligned} \right\} \rightarrow e_k = \left(3 - \frac{2}{\alpha}\right) \frac{E}{N} > 0 \rightarrow \alpha > \frac{2}{3}$$

- For  $\alpha < \frac{2}{3}$  the dynamics can't bring the system to  $\mathbf{e}_1 = \mathbf{e}_2 = \dots = \mathbf{e}_N$

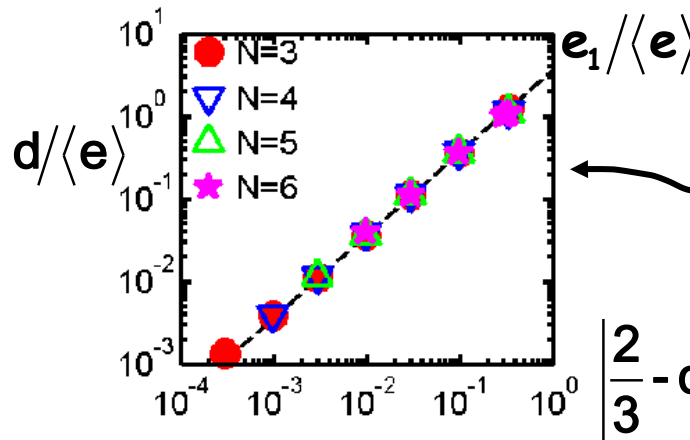
- Diameter of "hole" shrinks linearly with  $\alpha$ :  $d \equiv \left( \sum_{i=1}^N (e_i - \langle e \rangle)^2 \right)^{1/2} = \sqrt{\frac{3}{2}} \left( \frac{2}{3} - \alpha \right) \langle e \rangle$

# Isolated System is Far from Equilibrium



- Non-ergodicity disappears when system thermostated  
→ ensemble inequivalence (like long-range interactions?)

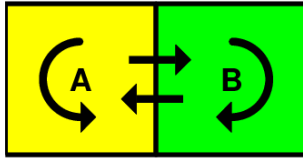
e.g. Mukamel, Ruffo, Schreiber 2005



- For  $\alpha < \frac{2}{3}$  the dynamics can't bring the system to  $e_1 = e_2 = \dots = e_N$

- Diameter of "hole" shrinks linearly with  $\alpha$ : 
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# Contact between Isolated Systems



- Different types of particles ( $A \neq B$ )
- Intra-system ( $\alpha_{AA}, \alpha_{BB}$ ) & inter-system ( $\alpha_{AB}$ ) interactions

Average energy change in each type of interaction:

i	j	k	$\Delta \langle e_A \rangle$
A	A	A	0
B	B	B	0
A	A	B	$-2(1 - \alpha_{AA}) \langle e_A \rangle$
B	B	A	$2(1 - \alpha_{BB}) \langle e_B \rangle$
A	B	A	$\langle e_B \rangle - \alpha_{AB}(\langle e_A \rangle + \langle e_B \rangle) / 2$
B	A	A	
A	B	B	$-\langle e_A \rangle + \alpha_{AB}(\langle e_A \rangle + \langle e_B \rangle) / 2$
B	A	B	

$$\longrightarrow \frac{d \langle e_A \rangle}{dt} = 2 \left[ (2 - \alpha_{BB}) \langle e_B \rangle - (2 - \alpha_{AA}) \langle e_A \rangle \right]$$

1) Steady state  $\rightarrow$  no equipartition:

$$T_G(A) = \langle e_A \rangle \neq \langle e_B \rangle = T_G(B)$$

2) Identify operational temperature:

$$T_{op} = (2 - \alpha) \langle e \rangle$$

- controls energy flow
- equalizes in steady state
- obeys 0<sup>th</sup> law (transitivity)
- coincides with equilibrium temperature at  $\alpha = 1$

# (Fluctuation-Dissipation Relations)

$$T_{\text{FD}} \equiv \frac{\text{Correlation}}{\text{Response}} = \dots = \frac{\langle e^2 \rangle}{2\langle e \rangle} = \frac{9 - 12\alpha + 5\alpha^2}{12\alpha - 10\alpha^2} \langle e \rangle$$

↑ Isolated System

- In principle  $T_{\text{FD}} \neq T_G = \langle e \rangle$ , but for  $\alpha > 0.5$ , deviations  $< 20\%$
- This may explain  $T_{\text{FD}} \approx T_G$  in granular gas simulations
- Isolated non-equilibrium systems in contact:

$$\text{Weak coupling} \quad \rightarrow \quad \frac{T_{\text{FD}}}{T_G} = \frac{\langle e^2 \rangle}{2\langle e \rangle^2} \quad \text{not affected} \quad \rightarrow \quad T_{\text{FD}}(\mathbf{A}) \neq T_{\text{FD}}(\mathbf{B})$$

Srebro, Levine 2004

Shokef, Levine 2006

Shokef, Bunin, Levine 2006

# Entropy may Decrease due to Contact

## • Isolated System

Single-particle energy distribution:  $p(\mathbf{e}) = \frac{1}{E} \varphi\left(\frac{\mathbf{e}}{E}; \alpha\right)$

↖ dimensionless function

$$s = -\int p(\mathbf{e}) \log(p(\mathbf{e})) d\mathbf{e} = \log(E) \int p(\mathbf{e}) d\mathbf{e} - \int \varphi\left(\frac{\mathbf{e}}{E}; \alpha\right) \log\left(\varphi\left(\frac{\mathbf{e}}{E}; \alpha\right)\right) \frac{d\mathbf{e}}{E} = \log(E) + s_0(\alpha)$$



Phase-space distribution:  $P(\mathbf{e}_1, \dots, \mathbf{e}_N) = \frac{1}{E^N} \varphi\left(\frac{\mathbf{e}_1}{E}, \dots, \frac{\mathbf{e}_N}{E}; \alpha\right)$

↓

$$S = -\int P \cdot \log(P) d\mathbf{e}_1 \dots d\mathbf{e}_N = \dots = N \cdot \log(E) + S_0(\alpha)$$

# Entropy may Decrease due to Contact

- **Isolated System**   $S(E; \alpha) = N \cdot \log(E) + S_0(\alpha)$

- **Disconnected systems**  $S = S_A + S_B = N \cdot \log(E_A) + N \cdot \log(E_B) + \text{const.}$   
   
 $\max(S) \Leftrightarrow E_A = E_B$

- **Start with  $E_A = E_B$ , connect systems, then disconnect**



**Dynamics lead to  $E_A \neq E_B$  which has lower entropy ???**

Why define  $S$  as  $-\int p \cdot \log(p)$  ?

Why not assume  $\frac{\partial S}{\partial E} = \frac{1}{T_{op}}$

and integrate to find  $S$  ?

**Isolated System:**

$$\frac{\partial S}{\partial E} = \frac{1}{T_{op}} = \frac{N}{(2-\alpha)E} \longrightarrow dS = \frac{N}{2-\alpha} \cdot \frac{dE}{E} \longrightarrow S = \frac{N}{2-\alpha} \log(E) + \text{const.}$$

**Two Systems:**

$$S = \frac{N}{2-\alpha_{AA}} \log(E_A) + \frac{N}{2-\alpha_{BB}} \log(E_B) + \text{const.}$$

$$\begin{array}{c} \downarrow \\ \max(S) \quad \Leftrightarrow \quad \frac{E_A}{E_B} = \frac{2-\alpha_{BB}}{2-\alpha_{AA}} \end{array}$$

**This is the energy partition  
reached by the dynamics**

**Entropy is maximized !!!**

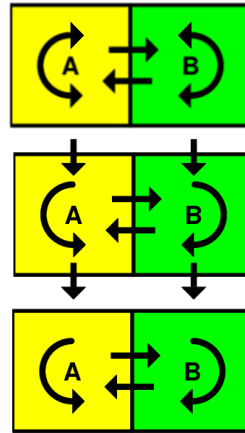
# Isolated Non-Equilibrium Systems in Contact

- 1) To study contact between non-equilibrium steady states, better disconnect the systems from the environment

- 2) Simple model:

$$\begin{array}{l} e_i \longrightarrow z\alpha(e_i+e_j) \\ e_j \longrightarrow (1-z)\alpha(e_i+e_j) \\ e_k \longrightarrow e_k+(1-\alpha)(e_i+e_j) \end{array}$$

Microscopic irreversibility  $\rightarrow$  Detailed-balance violation + Ergodicity breaking



- 3) Upon contact: - customarily used  $T_{\text{eff}}$ 's don't equilibrate  
- but we identified  $T_{\text{op}}$

- 4)  $S = -\int p \cdot \log(p)$  may increase, but  $S = \int \frac{dE}{T_{\text{op}}}$  is maximized